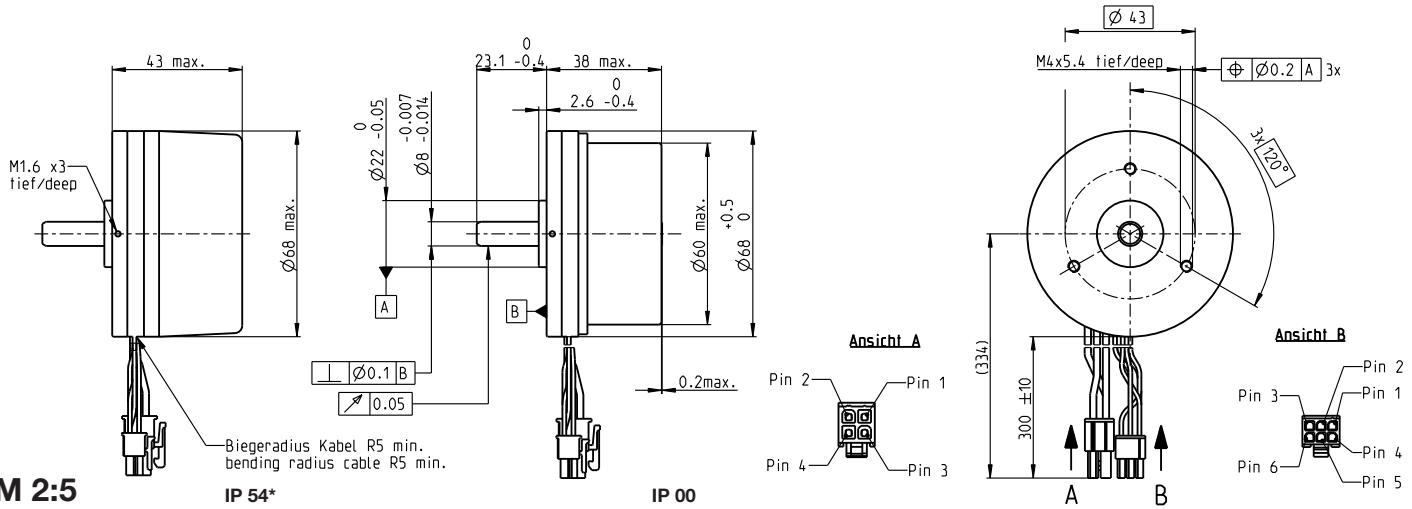


EC 60 flat $\varnothing 68$ mm, brushless, 100 Watt



M 2:5

IP 54*

IP 00

- Stock program
- Standard program
- Special program (on request)

Part Numbers	
IP 54* (with cover)	412819, 408057, 412821
IP 00 (without cover)	412823, 411678, 412825

Motor Data

Values at nominal voltage		412819		408057		412821	
		412823		411678		412825	
1 Nominal voltage	V	12	12	24	24	48	48
2 No load speed	rpm	3710	3710	4250	4250	3970	3970
3 No load current	mA	671	671	419	419	187	187
4 Nominal speed	rpm	3260	3170	3840	3740	3580	3490
5 Nominal torque (max. continuous torque)	mNm	231	279	227	289	257	319
6 Nominal current (max. continuous current)	A	7.81	9.25	4.43	5.47	2.3	2.78
7 Stall torque	mNm	2850	2850	4180	4180	5010	5010
8 Stall current	A	93.5	93.5	78.2	78.2	43.8	43.8
9 Max. efficiency	%	84	84	86	86	88	88
Characteristics							
10 Terminal resistance phase to phase	Ω	0.128	0.128	0.307	0.307	1.1	1.1
11 Terminal inductance phase to phase	mH	0.0615	0.0615	0.188	0.188	0.864	0.864
12 Torque constant	mNm/A	30.5	30.5	53.4	53.4	114	114
13 Speed constant	rpm/V	313	313	179	179	83.4	83.4
14 Speed/torque gradient	rpm/mNm	1.32	1.32	1.03	1.03	0.798	0.798
15 Mechanical time constant	ms	16.7	16.7	13	13	10.1	10.1
16 Rotor inertia	gcm ²	1210	1210	1210	1210	1210	1210

Specifications

- Thermal data**
- 17 Thermal resistance housing-ambient 4.34 (2.5) K/W
 - 18 Thermal resistance winding-housing 3.5 K/W
 - 19 Thermal time constant winding 40 s
 - 20 Thermal time constant motor 155 (86.9) s
 - 21 Ambient temperature -40...+100°C
 - 22 Max. winding temperature +125°C
- Mechanical data (preloaded ball bearings)**
- 23 Max. speed 6000 rpm
 - 24 Axial play at axial load < 12.0 N 0 mm
 - > 12.0 N 0.14 mm
 - 25 Radial play preloaded 0.14 mm
 - 26 Max. axial load (dynamic) 12 N
 - 27 Max. force for press fits (static) (static, shaft supported) 170 N
 - 8000 N
 - 28 Max. radial load, 5 mm from flange 112 N

Other specifications

- 29 Number of pole pairs 7
- 30 Number of phases 3
- 31 Weight of motor 470 g

Values listed in the table are nominal.

- Connection motor (Cable AWG 18)**
- red Motor winding 1 Pin 1
 - black Motor winding 2 Pin 2
 - white Motor winding 3 Pin 3
 - N.C. N.C. Pin 4

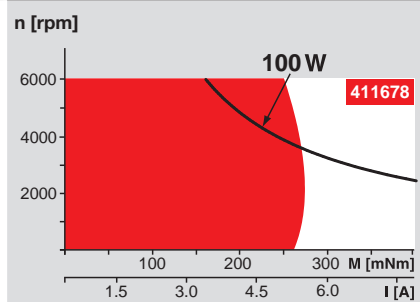
- Connector Part number**
- Molex 39-01-2040

- Connection sensors (Cable AWG 28)**
- grey Hall sensor 1 Pin 1
 - grey Hall sensor 2 Pin 2
 - grey Hall sensor 3 Pin 3
 - grey GND Pin 4
 - blue V_{Hall} 4.5...18 VDC Pin 5
 - N.C. N.C. Pin 6

- Connector Part number**
- Molex 430-25-0600

Wiring diagram for Hall sensors see p. 37
 * Protection class only when installed with flange-side seal.

Operating Range

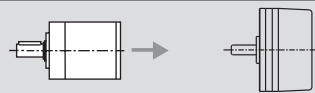


Comments

- Continuous operation**
In observation of above listed thermal resistance (lines 17 and 18) the maximum permissible winding temperature will be reached during continuous operation at 25°C ambient. = Thermal limit.
- Short term operation**
The motor may be briefly overloaded (recurring).
- Assigned power rating**

maxon Modular System

Planetary Gearhead
 $\varnothing 52$ mm
 4 - 30 Nm
 Page 355



Overview on page 20-27

- Recommended Electronics:**
- | Notes | Page 26 |
|----------------------|---------|
| ESCON Mod. 50/4 EC-S | 417 |
| ESCON Mod. 50/5 | 417 |
| ESCON 50/5 | 418 |
| ESCON 70/10 | 418 |
| DEC Module 50/5 | 420 |
| EPOS2 24/5 | 425 |
| EPOS2 50/5 | 425 |
| EPOS2 70/10 | 425 |
| EPOS2 P 24/5 | 428 |
| EPOS4 Module 50/8 | 431 |
| EPOS4 Comp. 50/8 CAN | 431 |
| MAXPOS 50/5 | 435 |

Encoder MILE
 512 - 4096 CPT,
 2 channels
 Page 380